

[Commands](#)[Update](#)[Parameters](#)[Spot Values](#)[Plot](#)[Refresh](#)☐ Auto

Commands

Save Parameters to FlashRestore Parameters from FlashRestore DefaultsStart Inverter in manual ModeStop InverterDisplay Error MemoryReset CAN Mapping Send Custom Command[Wifi Settings](#)

Update

Use binary files (stm32sine_HWCONFIG_XXX.bin) for updating inverter firmware. Upload any other file for updating this web interface.

If board is locked up:

1. Start update
2. Reset main board with reset button (be quick, time out after 5s)
3. Update should run normally

 No file chosen

Parameters

[Parameter Reference](#)

[Download Parameter File](#) Downloads the parameters as per the last table update

 No file chosen


Type new value and hit enter to change. Only change one value at a time.

Messages:

[1] : WARN - PWMSTUCK

[Commands](#)[Update](#)[Parameters](#)[Spot Values](#)[Plot](#)[Refresh](#)☐ Auto

Name	Value	Unit	Minimum	Maximum	Default
- Motor					
boost	<input type="text" value="2000"/>	dig	0	37813	1700
fweak	<input type="text" value="270"/>	Hz	0	1000	90
fconst	<input type="text" value="180"/>	Hz	0	1000	180
udcnom	<input type="text" value="360"/>	V	0	1000	0
fslipmin	<input type="text" value="1.25"/>	Hz	0	10	1
fslipmax	<input type="text" value="5"/>	Hz	0	10	3
fslipconstmax	<input type="text" value="5"/>	Hz	0	10	5
polepairs	<input type="text" value="2"/>		1	16	2
respolepairs	<input type="text" value="1"/>		1	16	1
encmode	<input type="text" value="AB"/> ▼		0	5	0
fmin	<input type="text" value="0.06"/>	Hz	0	400	1
fmax	<input type="text" value="500"/>	Hz	21	1000	200
numimp	<input type="text" value="36"/>	ppr	8	8192	60
dirchrpm	<input type="text" value="100"/>	rpm	0	2000	100
dirmode	<input type="text" value="Switch"/> ▼		0	3	1
syncofs	<input type="text" value="0"/>	dig	0	65535	0
snsn	<input type="text" value="KTY83-110"/> ▼		12	14	12
- Inverter					
pwmfrq	<input type="text" value="8.8kHz"/> ▼		0	4	1
pwmpol	<input type="text" value="ACTHIGH"/> ▼		0	1	0
deadtime	<input type="text" value="63"/>	dig	0	255	63
ocurlim	<input type="text" value="-2500"/>	A	-65536	65536	100
minpulse	<input type="text" value="1000"/>	dig	0	4095	1000
il1gain	<input type="text" value="-1"/>	dig/A	-100	100	4.68
il2gain	<input type="text" value="-1"/>	dig/A	-100	100	4.68
udcgain	<input type="text" value="7.5"/>	dig/V	0	4095	6.15
udcofs	<input type="text" value="0"/>	dig	0	4095	0
udclim	<input type="text" value="405"/>	V	0	1000	540
snsn	<input type="text" value="JCurve"/> ▼		0	5	0

Commands	Update	Parameters	Spot Values	Plot	 Refresh	<input type="checkbox"/> Auto
bmslimhigh	<input type="text" value="100"/>	%	0	100	50	
bmslimlow	<input type="text" value="-20"/>	%	-100	0	-1	
udcmin	<input type="text" value="0"/>	V	0	1000	450	
udcmax	<input type="text" value="520"/>	V	0	1000	520	
iacmax	<input type="text" value="5000"/>	A	0	5000	5000	
idcmax	<input type="text" value="5000"/>	A	0	5000	5000	
idcmin	<input type="text" value="-5000"/>	A	-5000	0	-5000	
throtmax	<input type="text" value="100"/>	%	0	100	100	
ifltrise	<input type="text" value="10"/>	dig	0	32	10	
ifltfall	<input type="text" value="3"/>	dig	0	32	3	
- Charger						
chargemode	<input type="text" value="Off"/> ▼		0	4	0	
chargecur	<input type="text" value="0"/>	A	0	50	0	
chargekp	<input type="text" value="80"/>	dig	0	100	80	
chargeflt	<input type="text" value="8"/>	dig	0	10	8	
chargemax	<input type="text" value="90"/>	%	0	99	90	
- Throttle						
potmin	<input type="text" value="820"/>	dig	0	4095	0	
potmax	<input type="text" value="4095"/>	dig	0	4095	4095	
pot2min	<input type="text" value="4095"/>	dig	0	4095	4095	
pot2max	<input type="text" value="4095"/>	dig	0	4095	4095	
potmode	<input type="text" value="SingleRegen"/> ▼		0	2	0	
throtramp	<input type="text" value="10"/>	%/10ms	0.09	100	100	
throtramprpm	<input type="text" value="20000"/>	rpm	0	20000	20000	
ampmin	<input type="text" value="5"/>	%	0	100	10	
slipstart	<input type="text" value="30"/>	%	10	100	50	
- Regen						
brknompedal	<input type="text" value="-20"/>	%	-100	0	-50	
regenramp	<input type="text" value="100"/>	%/10ms	0.09	100	100	
brknom	<input type="text" value="30"/>	%	0	100	30	

Commands	Update	Parameters	Spot Values	Plot	 Refresh	<input type="checkbox"/> Auto
brkrampstr	<input type="text" value="10"/>	Hz	0	400	10	
brkout	<input type="text" value="-50"/>	%	-100	-1	-50	

- Automation

idlespeed	<input type="text" value="-100"/>	rpm	-100	10000	-100
idlethrotlim	<input type="text" value="50"/>	%	0	100	50
idlemode	<input type="text" value="always"/>		0	2	0
speedkp	<input type="text" value="0.12"/>		0	100	0.25
speedflt	<input type="text" value="5"/>		0	16	5
cruisemode	<input type="text" value="Button"/>		0	1	0

- Contactor Control

udcsw	<input type="text" value="0"/>	V	0	1000	330
udcswbuck	<input type="text" value="540"/>	V	0	1000	540
tripmode	<input type="text" value="PrechargeOn"/>		0	2	0

- Aux PWM

pwmfunc	<input type="text" value="tmpm"/>		0	3	0
pwmgain	<input type="text" value="100"/>		-100000	100000	100
pwmofs	<input type="text" value="0"/>	dig	-65535	65535	0

- Communication

canspeed	<input type="text" value="250k"/>		0	3	0
canperiod	<input type="text" value="100ms"/>		0	1	0

- Testing

fslipspnt	<input type="text" value="0"/>	Hz	-100	1000	0
ampnom	<input type="text" value="0"/>	%	0	100	0


Spot Values


Show Gauges

Show Data Logger

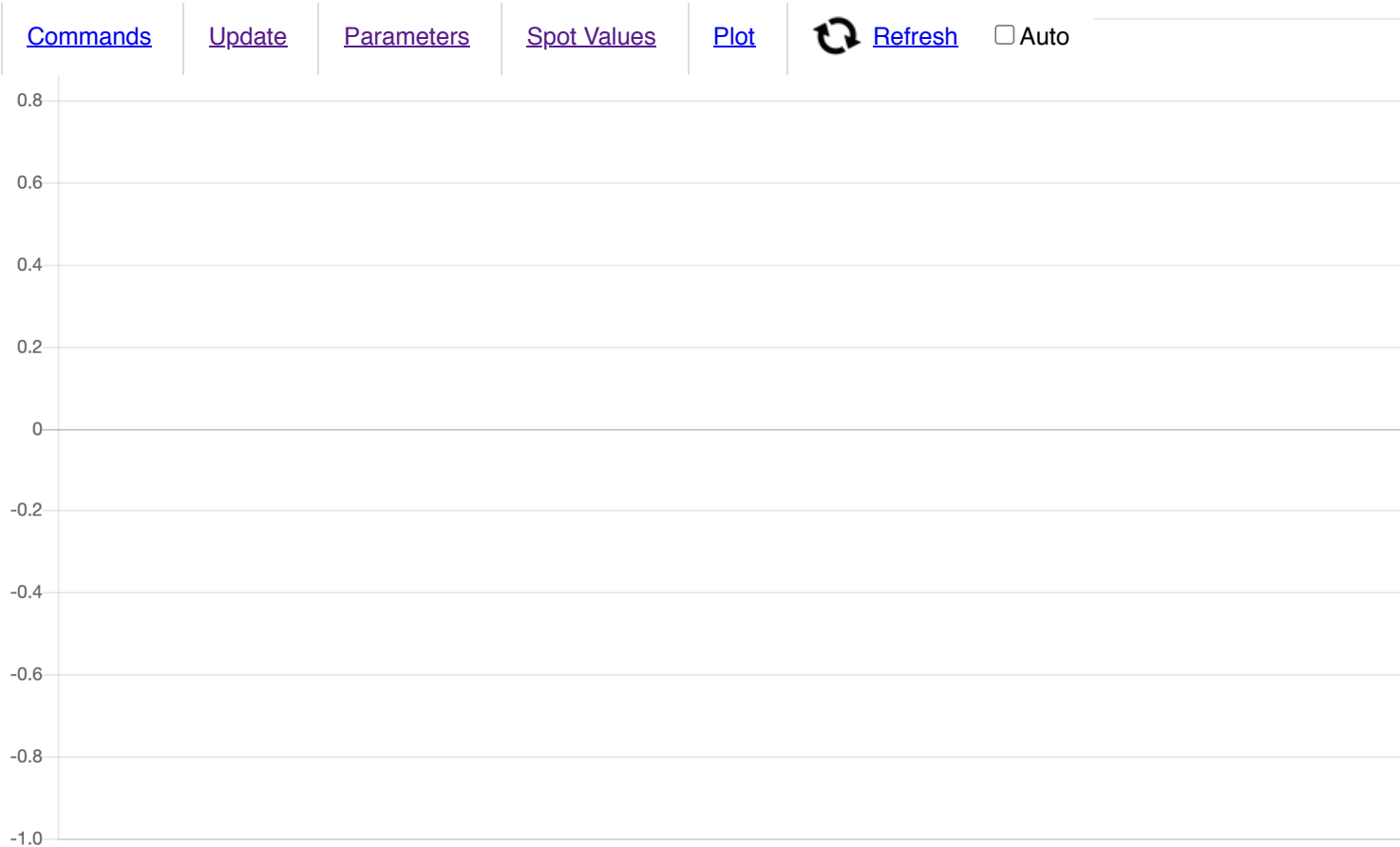
Name	Value	Unit	Plot	CAN Id	Position	Bits	Gain	Map to CAN
version	4.57.R-sine		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<div>TX</div> <div>RX</div>

Commands		Update		Parameters		Spot Values		Plot		Refresh		Auto		TX		RX	
opmode	Off																
lasterr	PWMSTUCK																
udc	1.31	V															
idc	0	A															
il1	0	A															
il2	0	A															
ilmax	0	A															
uac	0	V															
il1rms	0	A															
il2rms	0	A															
boostcalc	64000	dig															
fweakcalc	8.43	Hz															
fstat	0	Hz															
speed	0	rpm															

Commands	Update	Parameters	Spot Values	Plot	 Refresh	<input type="checkbox"/> Auto		
							TX RX	
amp	0	dig	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
angle	0	°	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
pot	960	dig	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
pot2	27	dig	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
potnom	-12.21	%	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
dir	Reverse		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
tmphs	18.12	°C	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
tmpm	15.31	°C	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
uaux	16.43	V	<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
pwmio	50944		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
canio			<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
din_cruise	Off		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
din_start	Off		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX
din_brake	Off		<input type="checkbox"/> I <input type="checkbox"/> r	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	TX RX

Commands		Update	Parameters	Spot Values	Plot	 Refresh	<input type="checkbox"/> Auto	
								<div>TX</div> <div>RX</div>
din_forward	Off		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
din_reverse	On		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
din_emcystop	Ok		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
din_ocur	Ok		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
din_desat	Ok		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
din_bms	On		<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>
cpuload	0.78	%	<div><input type="checkbox"/> I <input type="checkbox"/></div> <div>r</div>					<div>TX</div> <div>RX</div>

Plot



Start Plot

Stop Plot

Pause Plot

Limit data points to:

Burst length:

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